

- (b) A 3-phase, 50 Hz, 8 pole alternator has a star connected winding with 120 slots and 8 conductors per slot. The flux per pole is 0.05 wp, sinusoidally distributed. Determine the phase and line voltage. 10

**SECTION – D**

8. (a) Derive the power-angle equation and draw the power angle characteristics of salient pole synchronous machine. 10  
(b) Write a short note on : 10  
(i) V-curve of synchronous motor  
(ii) Damper winding
9. (a) What are the application of synchronous motor ? 10  
(b) Show that synchronous motor is a variable power factor motor. 10

Roll No. ....

**24225**

**B. Tech. 5th Sem. (EE)**

**Examination – December, 2016**

**ELECTRICAL MACHINES-II**

**Paper : EE-311-F**

*Time : Three Hours ]*

*[ Maximum Marks : 100*

*Before answering the questions, candidates should ensure that they have been supplied the correct and complete question paper. No complaint in this regard, will be entertained after examination.*

*Note : Attempt five questions in all, selecting one from each section & Question No. 1 is compulsory.*

1. Write short notes on : 4 × 5 = 20

- (a) What are the advantages of rotating field and stationary armature in synchronous machine ?  
(b) What does you mean by synchronous speed 3-phase induction motor ?

- (c) Deduce an expression for frequency of rotor current in an induction motor.
- (d) Define coil span and pole pitch.

### SECTION – A

2. (a) Describe mathematically development of rotating magnetic field in 3-phase induction motor. 10
- (b) Explain Torque-slip characteristics of 3-phase induction motor. 10
3. What are the various methods of speed control of 3-phase induction motor. 20

### SECTION – B

4. (a) Using Double Revolving Field Theory, explain why a single phase Induction motor is not self starting. 10
- (b) Explain various methods to make a single-phase induction motor self-start. 10

5. A 2-pole, 240 V, 50 Hz, single-phase induction motor has the following constants referred to the stator: 20

$$R_1 = 2.2\Omega; X_1 = 3.0\Omega; R'_2 = 3.8\Omega; X'_2 = 2.1\Omega$$

$$X_m = 86\Omega$$

Find the stator current and input power when the motor is operating at a full-load speed of 2820 r.p.m.

### SECTION – C

6. (a) Explain and derive the expression for: 10
- (i) Coil span factor ( $K_c$ )
- (ii) Distribution factor ( $K_d$ )
- (b) Draw and explain Equivalent circuit of alternator and draw the phasor diagram of a loaded alternator for the following conditions: 10
- (i) Lagging power factor
- (ii) Leading power factor
- (iii) Unity power factor
7. (a) Explain potier triangle method of determining the voltage regulation of an alternator. 10